

<b>Course Number and Name</b>												
BEE5L1 &Control Systems Laboratory												
<b>Credits and Contact Hours</b>												
2&45												
<b>Course Coordinator's Name</b>												
Dr.V.Jayalakshmi												
<b>Text Books and References</b>												
<b>Text Books:</b> Lab manual												
<b>References:</b> 1. LAB manual prepared by Department of Electrical & Electronics Engineering 2. <a href="http://www.mathworks.com/access/helpdesk/help/toolbox/control/">http://www.mathworks.com/access/helpdesk/help/toolbox/control/</a>												
<b>Course Description</b>												
To introduce control system lab experiments using hardware and software tools which provide path towards the engineering applications.												
<b>Prerequisites</b>						<b>Co-requisites</b>						
Nil						Control system						
required, elective, or selected elective (as per Table 5-1)												
Required												
<b>Course Outcomes (COs)</b>												
CO1: Ability tounderstand andanalyze the impact of PIDcontrollers on linear system. CO2:..Ability to conduct control system experiments andanalyze the concepts CO3:Ability to design compensators CO4: Ability to determine control system's parameters and transfer function parameters. CO5: Ability to use Matlab software for control system concepts.												
<b>Student Outcomes (SOs) from Criterion 3 covered by this Course</b>												
COs/SOs	a	b	c	d	e	f	g	h	i	j	k	l
CO1	M			H	M				M			M
CO2	M			H	M				M			M
CO3	M		M	H	M				M			M
CO4	H			H	M				M			M
CO5	M			H	H	H			H			H
<b>LIST OF EXPERIMENTS</b>												
<ol style="list-style-type: none"> <li>1. Determination of transfer function parameters of a DC servo motor.</li> <li>2. Determination of transfer function parameters of AC servo motor.</li> <li>3. Effect of P, PI and PID controllers on second order system.</li> <li>4. Digital simulation of linear systems</li> <li>5. Design of lag and lead compensators.</li> <li>6. Closed loop control system</li> <li>7. Stability analysis of linear systems.</li> </ol>												

8. Synchro Transmitter and Receiver characteristics.
9. MATLAB programming
  - a. Determination of Transfer function from poles and zeros.
  - b. Determination of Poles and zeros from transfer function.
  - c. Step and ramp response of first order system.
10. Simulation of second order system using MATLAB
11. Bode, Root Locus, Nyquist plots of Linear Time Invariant system using MATLAB.